

Necessary Conditions for Optimal Control Problems Governed by a Volterra Integral Equation

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Necessary conditions of optimal control problems involving integral equations have received the attention of several authors, see for example Bakke (Ref. [1]) and Carlson (Ref. [2]). More recently, models including nonlinear time delay in the state variable were formulated by Burnap and Kazemi (Ref. [3]).

In the present talk we consider the optimal control problem as follows:

$$\max_{(T,u,x)} J(T, u, x) = \int_0^T L(t, x(t), u(t)) dt + g(x(T)) \quad u(t) \in \mathcal{U},$$

where the system is governed by a Volterra integral equation

$$x(t) = h(t) + \int_0^t f(t, s, x(s), u(s)) ds \quad t \in [0, T],$$

and constraints depend on the terminal time and state:

$$\begin{aligned} \phi(T, x(T)) &= 0, \\ \psi(T, x(T)) &\leq 0. \end{aligned}$$

The control $u^*(t)$ defined in the interval $[0, T^*]$ is optimal if the triple (T^*, x^*, u^*) maximizes J over all of admissible triples (T, x, u) .

We establish necessary conditions for the optimal terminal time and control and new transversality conditions for the optimal time using Pontryagin-type perturbations.

Further, following the ideas of Bonnans (see [4] where it is proved a maximum principle for problems governed by an ordinary differential equation) and using Ekeland's variational principle we intend to give necessary conditions for an optimal control problem governed by a Volterra integral equation with restrictions on the state for all t , i.e.

$$\psi(x(t)) \leq 0; \quad t \in (0, T).$$

References

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